The Observing System Simulation Experiments for NPOESS

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64 PUBLICATIONS 635 CITATIONS

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303 PUBLICATIONS 3,486 CITATIONS

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1. INTRODUCTION

Global atmospheric observing systems, such as those on the Polar-orbiting Operational Environmental Satellites (POES), provide basic data for Numerical Weather Prediction (NWP) forecasts and the means to monitor and assess the climate. The National POES System (NPOESS) is scheduled to fly during the 2007-2010 period. For the next 10 years, a considerable amount of effort must take place to define, develop and build the suite of instruments which will comprise the NPOESS. The forecast impact of current instruments can be assessed by Observing System Experiments, in which already existing observations are denied or added to observations from a standard data base. However, the impact of future instruments, such as spaceborne Doppler wind lidar (DWL), must be assessed with experiments using simulated observations. These experiments are known as Observing System Simulation Experiments (OSSEs).

This project is a collaboration among several organizations. Data assimilation will be mainly tested by the National Centers for Environmental Prediction (NCEP) and the results will be backed up by NASA/Data Assimilation Office (DAO) and the Naval Research Laboratory (NRL). From the instrument community, Simpson Weather Associates (SWA) and others are participating to simulate Doppler Wind Lidar (DWL) observations, and the National Environmental Satellite, Data and Information Service (NESDIS) will simulate both existing and future thermodynamic sounders. DAO will simulate conventional observations.

Through this collaboration, the data assimilation and modeling communities will be involved in instrument design and can provide information about the expected impact of the new instruments. Furthermore, through the OSSEs, operational data assimilation systems will be ready to handle new data in time for the launch. This process involves the evaluation of the operational load, the development of the data base and data-processing, and a quality control system. All of this development will accelerate the operational use of data from the future instruments. (Lord et al. 1997)

For the OSSE, a long integration of an atmospheric general circulation model (GCM) is required to provide a "true atmosphere" for the experiment. This is called the "nature run". The nature run needs to be sufficiently representative of the actual atmosphere and also exhibit differences from the model used for the data assimilation. For this project, the nature run is provided by the European Centre for Medium-Range Weather Forecasts (ECMWF). The representativeness of the nature run was evaluated and found to be suitable to conduct OSSEs.

From the possible future instruments, DWL was selected as the first instrument to be tested by OSSEs. Data impact tests to elucidate the relative importance of wind and mass data for forecast accuracy are being conducted. DWL data, satellite radiance data and other conventional observation were simulated from this nature run for the OSSEs.

The further details of this work are presented in the OSSE web site at “http://nic.fb4.noaa.gov:8000/research/osse”.

2. EVALUATION OF THE NATURE RUN

A forecast model run for one month duration, made by the ECMWF at resolution T213 and 31 levels starting from 5 February 1993, is chosen as the first nature run to simulate the atmosphere (Becker et al 1996). The data were provided as either T213 spectral coefficients or reduced gaussian grid data at a resolution of approximately 60km at 31 model levels. The gridded data were expanded to a 640M-W320 regular gaussian grid and saved in GRIB format for use in the OSSE. The version of the model used for the nature run is same as in the ECMWF reanalysis (ERA), containing Tiedtke's mass flux convection scheme (Tiedtke 1989) and prognostic cloud scheme (Tiedtke 1993).

In general, February 1993 was typical for the Northern Hemisphere winter. The El Niño/Southern Oscillation condition during February 1993 was close to normal and there was no significant tropical sea surface temperature anomaly. A well organized tropical intraseasonal oscillation was active between November 1992 to mid-February 1993 but disorganized thereafter. The dominant midlatitude pattern during February 1993 was an Eastern North Atlantic pattern (Climate Diagnostics Bulletin, Climate Prediction Center/NCEP).
The cyclone activities in the nature run and in the ECMWF reanalysis are compared by R. Atlas and J.Terry of NASA/DAO (OSSE/NPOESS website). Remarkably similar cyclone tracks and activity are reported.

In order to produce realistic DWL data sampling, the nature run cloud distribution should be realistic. A detailed assessment of the nature run clouds is given by M. Masutani, K. Campana and S.-K. Yang of NCEP and S. Wood and D. Emmitts of SWA, and is on display at the OSSE/NPOESS website. The cloud parameterization by Tietke (1993) was used for the nature run.

The nature run clouds are compared with the U.S.A.F. Real-Time Nephanalyses (RTNEPH, Hamill, 1992) which is processed at NCEP, the International Satellite Cloud Climatology Project (ISCCP), stage D2, and the NESDIS experimental product, "Clouds from Advanced Very High Resolution Radiometer" data (CLAVR-phase 1). RTNEPH provides an estimation of the actual amount of high, middle and low level cloud; ISCCP provides satellite-viewed high, middle and low level cloud; currently only the total cloud is available from CLAVR.

Fig.1a shows a general agreement in the zonal mean distribution of total cloud. The large differences over the north and south polar region were difficult to evaluate, due to the difficulties of estimating clouds from a satellite over ice. In all likelihood, the nature run cloud may be closer to reality than the RTNEPH estimate and other satellite estimates in polar regions (R. Grumbine, personal communication). The nature run high level cloud amounts are much larger than the observed data and seem more realistic due to the underestimation of high level cloud in satellite based observation (Fig.1b). Marine stratocumulus is underestimated especially in mid-latitude, in this version of the ECMWF MRF model (C. Jakob 1999). There is also an overestimation of low level cloud over snow in the nature run (C. Jakob personal communication) (Fig.1d). These problems in low level cloud require some adjustment. Considering the observational uncertainty in cloud estimates, we judge that, after adjustment, clouds in the nature run are acceptable for this project. Adjustment is applied only to the low level cloud based on ground based observation. (Warren et. al. 1986, 1988)

3. SIMULATION OF CONVENTIONAL OBSERVATIONS

As part of the NPOESS OSSE project, NASA/DAO has the responsibility for the simulation, of realistic conventional observations and satellite observations consisting of cloud motion wind vectors, SSM/I wind speeds and scatterometer wind vectors.

Information from a real observation database is used to obtain the necessary spatial and temporal distribution to produce a representative sampling for the simulated observation database. The initial simulation experiment uses a subset of the same real observation data set used by the NCEP 40-year reanalysis project.

3.1 Observing Systems

The real conventional data that are simulated are comprised of observations from surface land stations, ships (both fixed and mobile), buoys (including drifting buoys, platforms and the TOGA TAO array moored buoys), rawinsondes and pilot balloons, aircraft (both conventional and ACARS) and PAOBS. Both cloud motion winds and water vapor winds are simulated using real observations from United States, European and Japanese polar-orbiting satellites. SSM/I and scatterometer wind observations are not available in the NCEP 40-year reanalysis observation data set and therefore are not simulated in the initial OSSE, but will be included in future OSSE's.

3.2 Observation Simulator

A bi-linear horizontal interpolation and a linear log pressure vertical interpolation are used for the interpolation
from the values at nature run grids points to observation points. A simple linear interpolation in time is also performed between the two bracketing six hour nature times to the time of the observation.

Due to differing surface pressures between the real and nature atmospheres, observations using nature surface information is fabricated whenever necessary to preserve near surface upper air observations. For land surface observations, the nature surface pressure is assigned to the station pressure. For ocean surface observations, the sea level pressure is assigned to the station pressure.

Real observations which are available above the nature atmosphere, that is above 10 mb, are not simulated. Given the data assimilation system that is being used for the NPOESS, OSSEs this should not impact the OSSE results.

3.3 Observational error

Uncorrelated random noise is added to perfect simulated observations using a Gaussian normal distribution of numbers along with observation error standard deviations. A set of random Gaussian normal values are generated for each report with the characteristics of having a mean of zero and a standard deviation of one. The observation error standard deviations are obtained from tables produced at ECMWF for each observing system, mandatory pressure level and atmospheric quantity.

Since the observation errors are available at only mandatory levels, significant level errors are obtained by interpolating, linearly in log pressure, the errors at vertically adjacent mandatory levels which bracket the observation to the observation level. For rawinsondes, an additional error is applied to significant level observations.

In the initial OSSE, the only observing system in which observation error standard deviations are unavailable is ACARS. Due to the improved accuracy of observations from ACARS over those obtained from conventional aircraft, conventional aircraft observation errors would be too pessimistic if applied to ACARS. Instead, rawinsonde errors are used since rawinsondes appear to resemble ACARS more closely than any other observing system with respect to the magnitude of the observation error.

3.4 Rawinsonde drift error

In addition to the Gaussian error, an attempt is made to simulate the error incurred by the downstream drift of a rawinsonde balloon from its launch site. The error is actually two-fold. An error in sampling may occur as a result of the horizontal displacement of the balloon from the launch site and as a result of the horizontal displacement of the column of air initially existing immediately above the launch site. The latter source of error is effectively due to the temporal displacement of the balloon. A simple set of equations has been derived which takes into account both of these sources of error to ultimately obtain a single error value at each level for each measured atmospheric quantity.

3.5 Application of wind error

Wind error standard deviations are directly available in only component form. However, it is more consistent to apply errors to wind observations in the form of a direction and speed rather than as u and v components since wind direction and speed are the characteristics of the wind field that are measured directly by conventional instruments. To achieve this, a wind direction and speed error standard deviation is derived analytically using the relationship between the directiona and speed and the u and v components.

4. DWL DATA SIMULATION

Space-based application of Doppler Wind Lidar (DWL) technology is without heritage. Thus, optimal design of DWL systems for space deployment must rely upon simulated experiments. The simulation of DWL data include efforts with DWL performance models, atmospheric circulation models and atmospheric optical models (Atlas and Emmitt, 1995; Emmitt, 1995a; Emmitt and Wood, 1996; Wood et al., 1993; Wood et al., 1995).

The steps between a notional concept for a DWL and the blueprints for instrument construction include a considerable amount of performance modeling and, for space-based systems, an intensive series of OSSEs. During and subsequent to the Laser Atmospheric Wind Sounder (LAWS) study (Baker et al., 1995), a method for assessing the potential impact of a new DWL observing system was established. The instrument parameters are provided by the engineering community. Scanning and sampling requirements are provided by the science community and define various instrument scenarios. These scenarios are tested initially by examining the sensitivity of analyses to the various scenarios. A candidate(s) DWL concept is then chosen for a full OSSE, and an impact study is then conducted and evaluated by a technology neutral group.

The first simulated DWL wind data is produced as the line-of-sight wind by SWA using their Lidar Simulation Model (LSM). The configuration of the control experiment shown in Table 1. Number of experiments with different resolution and various assumption regarding cloud characteristics will be tested.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Horizontal resolution</td>
<td>200 km X 200 km</td>
</tr>
<tr>
<td>Vertical resolution</td>
<td>1 km above the PBL and 250 m in the PBL</td>
</tr>
<tr>
<td>Satellite height</td>
<td>833 km</td>
</tr>
<tr>
<td>Nadir scan angle</td>
<td>45 deg</td>
</tr>
<tr>
<td>Pulse rate frequency</td>
<td>12.5 Hz</td>
</tr>
</tbody>
</table>

Table 1

5. DATA ASSIMILATION SYSTEM AND IMPACT TEST

The data assimilation system at NCEP is based on the
“Spectral Statistical Interpolation (SSI)” of Parrish and Derber, 1991, which is a three-dimensional variational analysis (3-D var.) Scheme. In 1995, the assimilation system was modified to use TOVS cloud-cleared radiances instead of using temperature and moisture vertical retrievals, and significant improvements were reported by Derber and Wu (1998). In January 1998, the use of pre-processed radiance data (traditionally referred to as level-1b data) became operational (McNally et al., 1998) and an upgrade to this system was implemented in June 1998. The March 1999 version of NCEP’S operational Medium Range Forecast (MRF) and data assimilation system is used for the current data impact test. Line of sight (LOS) winds from DWL are directly used in the data assimilation.

Impacts of TOVS level-1b radiance, RAOB temperature, and RAOB wind is tested for the nature run period. The initial experiments are conducted using T62 horizontal resolution and 28 vertical levels. The tests will be repeated with simulated data. In order to perform reliable OSSEs for future instruments, the data impact of simulated data for existing instruments must be similar to that of real data.

6. CONCLUDING REMARK

In addition to a DWL, the Cross track Infrared Sounder (CrIS), Conically scanning Microwave Imager/Sounder (CMIS), and the Advanced Technology Microwave Sounder (ATMS) have been proposed as candidate instrument to be tested by OSSEs. We are proceeding to develop appropriate forward models for these instruments.

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REFERENCES


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Fig. 2 Simulated observed RAOB wind (dark) and wind from the nature run at 500hPa. 12Z 5 February 1993. Bottom left corner: 26N 25W. Top right corner: 66N 55E. Unit Knots.
Fig. 3  Simulated DWL LOS wind observation along the orbit.  Half Orbit of accumulated between 00Z and 03Z on 7th February 1993.